Name: _

ID (helpful but not necessary): ____

Clear your desk of everything except pens, pencils and erasers. Show all work clearly and in order. No notes, phones and calculators. You have 50 minutes to finish the 6 pages for 100 points.

- 1. (20 points) Check that whether the following statements are True or False. (a-f: 3 points; g: 2 points).
 - (a) True or False. The following linear system is inconsistent since geometrically the two equations represent two straight lines that do not intersect each other.

The two equations represent the $2x_1 - x_2 = 3$ same line. Thuse are infinitely many $-4x_1 + 2x_2 = -6$ points in the line. The system has infinitely many shortlans, therefore, is consistent. (b) True or False. The following matrix is in its reduced row echelon form.

$$\begin{bmatrix} 1 & -3 & 0 & 2 \\ 0 & 0 & 1 & -2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

(c) True or False. If

then

$$A = \begin{bmatrix} 2 & 4 \\ 1 & 3 \end{bmatrix}, \quad B = \begin{bmatrix} -2 & 1 \\ 0 & 4 \end{bmatrix}$$
$$4 = \begin{bmatrix} -4 & 18 \\ 2 & 13 \end{bmatrix}$$
$$AB = \begin{bmatrix} -4 & 18 \\ 2 & 13 \end{bmatrix}$$

(d) True or False It is not possible to multiply the first matrix times second because their dimensions (sizes) are not the same.

$$\begin{bmatrix} 3 & 5 & 1 \\ -2 & 0 & 2 \end{bmatrix} \begin{bmatrix} 2 & 1 \\ 1 & 3 \\ 4 & 1 \end{bmatrix} = \begin{bmatrix} 3a+5\cdot|+|+4 & 3\cdot|+5\cdot3+|\cdot| \\ 32+0+24 & -2\cdot|+0+2\cdot| \end{bmatrix}$$
(e) True or False. Let A, B be two $n \times n$ matrices, then $(AB)^T = A^T B^T$. $B^T A^T$
(f) True or False. Let C be a nonsymmetric $n \times n$ matrix, then the following matrix is symmetric.
 $F = (I + C^T)(I + C) = \mathbb{Z} + C^T + C + C^T C \begin{bmatrix} \forall Tauface, F = 1^T + (C^T) + C^T + (C^T) \\ = 1 + (c^T)^T + C^T + C^T + C + C^T C \\ = 1 + (c^T)^T + C + C^T + C + C^T - C \\ = 1 + (c^T)^T + C + C^T + C + C^T - C \\ = 1 + (c^T)^T + C + C^T + C + C$

2. (20 points) Consider the following linear systems.

$$2x_1 + x_2 + 3x_3 = 0$$

$$4x_1 + 3x_2 + 5x_3 = 1$$

$$6x_1 + 5x_2 + 5x_3 = -3$$

4pt(a) Find the augmented matrix of the linear system.

Ī	2	1	3	[0]	
	4	3	5		2.pt
	6	5	5	3	

by Solve the system if it is consistent or state why it is inconsistent. Show your work.

 $= \begin{cases} 2 & | & 3 & 0 \\ 0 & | & -| & | & R_{m} \otimes -\lambda \times R_{m} \\ 0 & 2 & -4 & | & -3 & R_{m} \otimes -3 \cdot R_{m} \\ 0 & 2 & -4 & | & -3 & R_{m} \otimes -3 \cdot R_{m} \\ 0 & 2 & -4 & | & -3 & R_{m} \otimes -3 \cdot R_{m} \\ 0 & 2 & -4 & | & -3 & R_{m} \otimes -3 \cdot R_{m} \\ 0 & 2 & -4 & | & -3 & R_{m} \otimes -3 \cdot R_{m} \\ 0 & 2 & -4 & | & -3 & R_{m} \otimes -3 \cdot R_{m} \\ 0 & 2 & -4 & | & -3 & R_{m} \otimes -3 \cdot R_{m} \\ 0 & 2 & -4 & | & -3 & R_{m} \otimes -3 \cdot R_{m} \\ 0 & 2 & -4 & | & -3 & R_{m} \otimes -3 \cdot R_{m} \\ 0 & 2 & -4 & | & -3 & R_{m} \otimes -3 \cdot R_{m} \\ 0 & 2 & -4 & | & -3 & R_{m} \otimes -3 \cdot R_{m} \\ 0 & 2 & -4 & | & -3 & R_{m} \otimes -3 \cdot R_{m} \\ 0 & 2 & -4 & | & -3 & R_{m} \otimes -3 \cdot R_{m} \\ 0 & 2 & -4 & | & -3 & R_{m} \otimes -3 \cdot R_{m} \\ 0 & 2 & -4 & | & -3 & R_{m} \otimes -3 \cdot R_{m} \\ 0 & 2 & -4 & | & -3 & R_{m} \otimes -3 \cdot R_{m} \\ 0 & 2 & -4 & | & -3 & R_{m} \otimes -3 \cdot R_{m} \\ 0 & 2 & -4 & | & -3 & R_{m} \otimes -3 \cdot R_{m} \\ 0 & 2 & -4 & | & -3 & R_{m} \otimes -3 \cdot R_{m} \\ 0 & 2 & -4 & | & -3 & R_{m} \otimes -3 \cdot R_{m} \\ 0 & 2 & -4 & | & -3 & R_{m} \otimes -3 \cdot R_{m} \\ 0 & 2 & -4 & | & -3 & R_{m} \otimes -3 \cdot R_{m} \otimes -3 \cdot R_{m} \\ 0 & 2 & -4 & | & -3 & R_{m} \otimes -3 \cdot R_{m} \otimes -3 \cdot R_{m} \\ 0 & 2 & -4 & | & -3 & R_{m} \otimes -3 \cdot R_{m} \otimes -3 \cdot$ 3pt/16 $\longrightarrow \begin{bmatrix} 2 & 1 & 3 & 0 \\ 0 & 1 & -1 & 1 \\ 0 & 0 & -2 & 1 & -5 \end{bmatrix} Au(S) - 2 \cdot Bu(S). \frac{3pt}{16} - \frac{1}{16}$ The reduced system. [2X1 + X1 + 3X3 = 0 26 - X2 = 1 -2 X3 = -5 1pt Rack substitution : -233=-5 => 33= $x_{2} - x_{3} = | \Rightarrow x_{2} = x_{3} + | = \frac{5}{2} + | = \frac{1}{2}$ 3pt 2×1+×2+3×3=0⇒2×1=-×2-3×3=-=-==-1) $x_1 = \left(\frac{11}{z}\right)$ 3pt The solution is $\gamma_1 = -\frac{1}{2}$, $\gamma_2 = \frac{1}{2}$, $\gamma_3 = \frac{1}{2}$. 四(一些, 王、字)

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4. (20 points) let

$$A = \begin{bmatrix} 1 & 3 & 2 \\ 4 & 1 & -2 \\ 2 & 1 & 3 \end{bmatrix}$$

(a) Evaluate the determinant det(A). (You can compute either by the definition of the determinant directly or by applying the row operation to simply the matrix first.)

$$d_{4}A = 1 \cdot \begin{vmatrix} 1 & -2 \\ 1 & 3 \end{vmatrix} -3 \cdot \begin{vmatrix} 4 & -2 \\ 2 & 3 \end{vmatrix} + 2 \cdot \begin{vmatrix} 4 & 1 \\ 2 & 1 \end{vmatrix}$$

$$= 1 \cdot (3 - (-2)) - 3 \cdot (4 \cdot 3 - (-2) \cdot 2) + 2 \cdot (4 \cdot -2)$$

$$= 1 \cdot (3 - (-2)) - 3 \cdot (4 \cdot 3 - (-2) \cdot 2) + 2 \cdot (4 \cdot -2)$$

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(b) Use your answer to part (a) to find det(-A). *Hint: consider* -A = (-1)A. det $(-A) = (-1)^3$. det A

$$= -1 \cdot (-39)$$
 29t
 $= 39.$ 29t.

5. (10 points) Let

$$R = \begin{bmatrix} \frac{1}{2} & -\frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & \frac{1}{2} \end{bmatrix}^{T}$$
Prove that $R^{-1} = R^{T}$.
Frince $\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}^{T} = \frac{1}{a_{11}b_{22}-b_{22}b_{23}} \begin{bmatrix} a_{22} & -b_{22} \\ -b_{23} & a_{23} \end{bmatrix}$

$$R^{T} = \frac{1}{\frac{1}{2} \cdot \frac{1}{2} - (\frac{1}{2})(\frac{15}{2})} \cdot \begin{bmatrix} \frac{1}{2} & \frac{15}{2} \\ -b_{23} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{15}{2} \\ -b_{23} & \frac{1}{2} \end{bmatrix}$$

$$R^{T} = \begin{bmatrix} \frac{1}{2} & -\frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{15}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac$$

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6. (10 points) Let

$$A = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

$$\begin{aligned} \mathbf{b} \mathbf{p} \mathbf{L} (\mathbf{a}) \text{ Prove that } A^{n} &= \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \text{ for all positive integers } n \geq 3. \\ A^{2} &= \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0$$

 $4 \neq (b)$ Prove that I - A is invertible and has the following inverse formula:

$$(I-A)^{-1} = I + A + A^{2}$$
There computation (and by $A^{3}=0$ in (a)):

$$(I-A) \cdot (I+A+A^{2}) = I+A+A^{2} - A \cdot (I+A+A^{2})$$

$$= I+A+A^{2} - A-A^{2} - A^{3} = I - A^{3} = I.$$

$$(I+A+A^{2}) \cdot (I-A) = I+A+A^{2} - (I+A+A^{2})A$$

$$= I+A+A^{2} - (I+A+A^{2})A$$

$$= I+A+A^{2} - A-A^{2} - A^{3} = I-A^{3} = I.$$
Therefore, by the definition of the inverse, $(I-A)^{-1} = I+A+A^{2}$
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